



ASL-TR-0027

CONG-RANGE ARTILLERY SOUND RANGING:

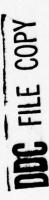
"PASS" GR-8 SOUND RANGING DATA

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MARCH 1979

Ву

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Approved for public release; distribution unlimited



US Army Electronics Research and Development Command

Atmospheric Sciences Laboratory

White Sands Missile Range, NM 88002

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20. ABSTRACT (cont)

meteorological correction and these automatic aids, this analysis suggests a significant improvement over the manual process of selecting the arrival times. With these aids the record reader was able to provide more timely arrival time data that permitted sound source location with miss-distances less than 1.5 percent) of the over 10 km range targets.

SUMMARY

The first step for rereading all the GR-8 record tapes was to use the manually selected arrival times to derive the direction rays and automatically plot their intersections. Using this as an aid the record reader could identify which microphone record needed verification. In the case of unknown target location, this type of editing was limited to checking only the rays that deviated significantly from the well-defined intersection cluster. It should be pointed out that for field data a single point intersection does not necessarily provide the best estimate of source location. Using the centroid method for determining the final location, the spread of the polygon of error (defined by the ten intersections of the five rays) may be as high as an equivalent 400-m radius.

Another aid was added to the automatic plot, which required an initial estimate of the sound source direction. If an accurate initial guess of the direction of the sound source were not available, the problem could be solved by using the manual method, and the computed direction of the source location would then be used. The available meteorological message was also used in computing the theoretical arrival time. The second time the record reader examined the GR-8 tape, the computed arrival time for each microphone was displayed. The reader looked at that particular point and then adjusted to keep the same selection criteria (break, valley, crossover, or peak) for all six microphone traces. The appendix contains the selected arrival times, and the plots of the direction rays confirm the spread for each fix contained in the research data base.

With the use of newer techniques, including editing procedures to more accurately select arrival times and use of accurate meteorological data, longer range sound ranging targets were located within 1.5 percent of the target range.

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INTRODUCTION

State of the art has enhanced the artillery capability so that today tactical artillery support is effectively provided at much longer ranges. In response to this new capability, a current target acquisition approach is reexamined with the emphasis on locating enemy artillery targets at ranges greater than 10 km. Since World War I, artillery sound ranging has yielded more confirmed target locations than all other methods combined. This method is a passive technique and requires an array of microphones that provide the artillery record reader with data identifying the sound arrival time at each microphone. It is fundamentally a direction finding technique which uses the sound arrival time data to derive direction rays. The artilleryman then uses the intersection of the different rays to estimate a sound source location.

Between October and December 1974, a ground recorder (GR-8) sound ranging set with six microphones was operated during the Atmospheric Sciences Laboratory meteorological comparisons test (Project PASS).¹ During this experiment the sound wave from explosions at surveyed locations were monitored by using a surveyed linear-array of hot-wire-type microphones (T-23). A basic review of the manual record reading procedure is included in the report for providing general information. The data base for the GR-8 sound arrival times is also included in the report. Some results concerning the interactions between the best available meteorological conditions,² the microphone record readings, and the centroid method employed for determining the sound source locations are presented.

Automated assistance in record reading is emphasized, with a significant improvement demonstrated on the solution of the long-range artillery sound ranging problem. Data collected during the experiment and read immediately thereafter were used to compute the sound source location. These results were then compared to those derived by employing automated aides in record reading of sound arrival times.

EXPERIMENTAL APPROACH

To demonstrate the accuracy of sound ranging at ranges greater than 10 km, a comprehensive experiment was performed to acquire the required sound ranging data. Data from surveyed microphones were used to calculate the position of the surveyed sound sources.

¹K. M. Barnett, 1976, "A Description of the Artillery Meteorological Comparisons at White Sands Missile Range, October 1974-December 1974 ("PASS" - Prototype Artillery [Meteorological] Subsystem)," ECOM-5589, Atmospheric Sciences Laboratory, White Sands Missile Range, NM

²A. J. Blanco, 1978, "Long-Range Artillery Sound Ranging: "PASS" Meteorological Application," ASL-TR-0014, Atmospheric Sciences Laboratory, White Sands Missile Range, NM

The GR-8 Sound Ranging System³ as used on this test consisted of six (T-23) "hot wire" microphones in a four-sound-second linear array. The remote timer unit (PE 244) and recorder (BC 1337) were powered by a 12-volt storage battery. This battery was constantly charged by a dc power source operating on normal 110-volt power. The microphones responded to atmospheric pressure changes created by 5-pound C4 explosive charges, 8-inch howitzer gun blasts, and shell bursts. Figure 1 illustrates the relative position of the sound sources with respect to the linear array of microphones, and table 1 lists the surveyed locations.

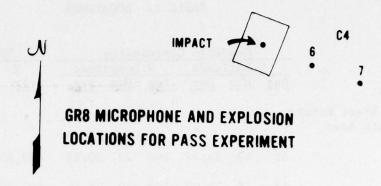
The selection of the arrival time for these air pressure changes at each microphone is used to determine the surveyed location of the source of these pressure changes. A considerable effort was made to immediately analyze the strip chart records. The time of arrival of the sound waves at each microphone was selected and entered on coding forms for later automated computations for locating the source location. All sound ranging equipment was supplied by the Target Acquisition Branch of Counter Fire Department, US Army Field Artillery School (USAFAS) at Fort Sill, Oklahoma. School personnel supervised the installation, maintenance, operation, and original data reduction of the GR-8 equipment throughout the comparisons at White Sands Missile Range (WSMR), New Mexico.

RECORD READING

After the equipment is checked out for operation, the attenuators located within the GR-8 recorder must be balanced. These attenuators are numbered to correspond to the microphone output they control, and each is individually adjusted. Currently there is no doctrine for an ideal setting. Only experience gained through operation under the current local conditions can determine the ideal setting. The adjustment of the attenuators determines the difference between recording usable and non-usable records. The amplitude of the microphone signals is translated into a written record on the recording paper which contains time markings as series of dots (1/10 second and 1/100 second markers) along one edge of the paper. The record can be read to 10 milliseconds and interpolated to 1 millisecond. According to Field Manual FM 6-122, the errors inherent in visual interpolation will yield arrival times accurate to within 0.003 second.

³TM 11-2568, 1945, "Sound Ranging Set GR-8," War Department Technical Manual, Headquarters, Department of the Army, Washington, D.C.

[&]quot;FM 6-122, 1964, "Artillery Sound Ranging and Flash Ranging," Department of the Army Field Manual, Headquarters, Department of the Army, Washington, D.C.





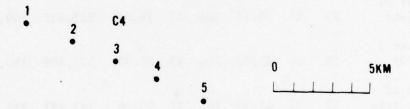


Figure 1. The relative position of the sound sources with respect to the linear array of microphones.

TABLE 1. LOCATIONS

	Geodetic Coordinates				WSTM	Coordina	tes		
		Lat	itude	W	Long	itude	X	Y	Z
	Deg	Min	Sec	Deg	Min	Sec	<u>Ft</u>	<u>Ft</u>	<u>Ft</u>
C4 Blast Point South Area	s								
1	32	19	11.42	106	22	00.55	489,655	155,724	4,016
2	32	18	36.90	106	20	25.66	497,798	152,235	4,004
3	32	18	02.37	106	18	50.79	505,941	148,745	4,059
4	32	17	27.83	106	17	15.94	514,083	145,258	4,072
5	32	16	53.25	106	15	41.11	522,226	141,768	4,078
C4 Blast Point North Area	ts								
6	32	31	07.71	106	10	20.74	549,600	228,147	4,026
7	32	30	33.06	106	08	45.73	557,742	224,658	4,086
Howitzer 1 (12Z480) (center of trunnion)	32	24	45.14	106	15	26.64	523,435	189,456	4,041
Howitzer 2 (12HM73)	32	24	45.26	106	15	26.93	523,409	189,468	4,041
Center of Impact Area	32	31	42.35	106	11	55.79	541,457	231,636	4,034
T-23 microphor (left to right									
1	32	24	27.83	106	17	56.54	510,584	187,700	4,040
2	32	24	10.49	106	17	09.04	514,657	185,949	4,049
3	32	23	53.30	106	16	21.56	518,730	184,214	4,046
4	32	23	35.97	106	15	34.10	522,800	182,465	4,046
5	32	23	18.70	106	14	46.67	526,868	180,723	4,044
6	32	23	01.42	106	13	59.21	530.940	178,980	4,061

The point at which the trace first departs from its straight line path (or zero line) is the initial break. The low and high points on the periodic trace are called valleys and peaks, respectively. A curve representing the variation of pressure with time at a given point on a path of the sound wave is shown in figure 2. The total elapsed time from the initial break through one cycle of oscillation is the period of the sound wave.

During this field experiment a four-sound-second displacement between adjacent microphones was selected to sound range on source targets at ranges greater than 10 km. This experiment did not duplicate collection of sound ranging data but enhanced the Army sound ranging data base to contain longer ranges at various flank angles. The linear microphone array was selected to establish an expected pattern of the arrival of the sound wave at the various microphones of the sound ranging base. For example, the C4 explosion on location 1 gave the typical pattern illustrated on figure 3. The microphones are labeled from right to left as one faces the direction of observation for sound ranging. The current doctrine is to sound range in a forward zone coverage defined within a ±50-degree angle from the perpendicular bisector of the microphone linear array.

The selection criteria were constrained to using the same signature point on all microphone traces within a given pattern for the triangulation of the sound source. There are four acceptable reading points: first choice, the initial break; second choice, the point at which the zero line is first crossed; third choice, at the center of the first valley; and fourth choice, at the center of the first peak.

In this controlled experiment, situations leading to contaminated records were eliminated. The microphone traces do not contain ballistic waves or signature from multiple targets or friendly fire. However, data from Project PASS contain multiple arrivals of the same sound wave at a microphone position, thereby making it difficult to select the same signature point from all microphone traces. The sound arrival times at each microphone are manually selected and provided as input to the computing device. Meteorological parameters are measured and a sound ranging met message is calculated for input with the end result being the computation of a sound source estimate.

²A. J. Blanco, 1978, "Long-Range Artillery Sound Ranging: "PASS" Meteorological Application," ASL-TR-0014, Atmospheric Sciences Laboratory, White Sands Missile Range, NM

IMPULSE WAVE OF AN 8 INCH HOWITZER

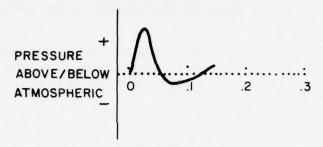


Figure 2. Impulse wave of an 8-inch howitzer has an approximate frequency of 8 cycles per second or 0.125-second period.

EXPECTED PATTERN OF ARRIVAL TIME OF A SOUND WAVE

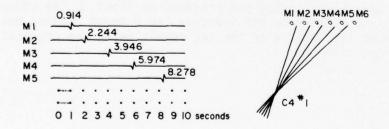


Figure 3. Expected pattern on a straight base record for C4 explosive charge at location 1.

SOUND RANGING METHOD

The sound ranging method utilized is a simple geometric⁵ model. This method depends on the relative arrival times at a pair of microphones. If it is assumed that the gun and all microphones are in the same plane. then the time difference between two adjacent microphones multiplied by the velocity of sound in the air equals the difference in distance traveled by the sound wave. Since by definition a hyperbola is the locus of points the difference of whose distance from two fixed points is constant, the sound source lies on a hyperbola whose foci are at the two adjacent microphones. Associated with each hyperbola is its asymptote which is a straight line passing through the midpoint between the foci and tangent to the hyperbola at infinity. Figure 4 shows the geometric construction that follows to calculate the direction of the sound source. The ten intersections of five direction rays are then used to determine the sound source. The figure also shows that the points of intersection for the asymptotes and the hyperbolas are not the same; therefore, a "curvature" correction is required when this geometric method is used for sound ranging.

EXPERIMENTAL DATA EDITING

The first set of fixes was calculated from the microphone record reading performed immediately after the experimental event and from meteorological messages manually calculated at the time of the experiment. The fixes containing large location errors were flagged and the corresponding microphone traces were reread. A second set of fixes was then computed using the new arrival times with edited met messages. This is the original data base for the field comparison performed at WSMR in 1974. Preliminary analysis indicated that there were large errors associated with PASS artillery sound ranging. Thus the original data base was suspected of being in error, and manual plots of the direction rays revealed a need for rereading all the original microphone records.

The automatic plotting indicated numerous cases where one direction ray was almost parallel to another. Since the intersection points will be widely distributed, the final estimate will contain a large miss. There were cases when the large polygon (2000 m) defined by the intersection of the direction rays yielded a good location but only after the centroid procedure was performed to obtain the fix. Quality research cannot be based on this type of information; therefore, a complete new reading of the microphone traces was necessary. The original meteorological data was edited for errors and a new calculation of the FM 6-15 sound ranging

⁵R. P. Lee, 1969, "A Dimensional Analysis of the Errors of Atmospheric Sound Ranging," ECOM-5236, Atmospheric Sciences Laboratory, White Sands Missile Range, NM

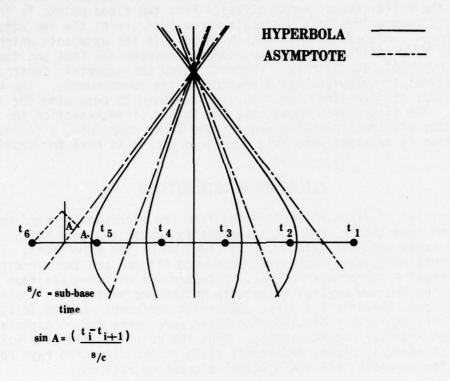


Figure 4. Fixing on a sound source by using arrival time data from a linear array of six microphones.

met messages was completed. With the automated plot available, the record reader reread the particular microphone responsible for producing wrong direction rays. This editing was performed only in cases where the particular ray was significantly separated from the cluster of the other intersections. The editing procedure automatically plots the five direction rays derived from the adjacent microphones of the regular linear array. The same procedure is currently manually performed in field application. The selected arrival times are suspected of being in error when they deviate from the assumed pattern of arrival times. The artilleryman, plotting the direction rays, identifies particular microphones that need verification of arrival time reading.

The automated processes available for the reading of the original records included the plotting of the direction rays (EDIT 1) and an aid in selecting the particular arrival time produced by a single wave passing through all six microphones (EDIT 2). Figure 5 illustrates the type of problem the record reader encounters when he needs to select from multipath arrivals. A single signature point from the common wave needs to be selected from all six microphones. The triangulation represents the fix on location 3. The first intersection represents the polygon of error defined by the "immediately read arrival times." A fix with a radial miss of about 100 m was computed. The next intersection is one derived by using manual editing from the automated plotting. Finally, the last intersection is obtained from using the automated aid of selecting the arrival times from a single pressure wave passing through all six microphones. A survey of the original microphone traces (bottom of figure 5) reveals the quality of the available data. Note that the polarity is not the same for all microphones; however, EDIT 2 aids the record reader in selecting the appropriate arrival times considering the initial polarity connection between the microphones and recorder.

The formulation for the EDIT 2 process was developed using the current method of sound ranging. The procedure is expressed in the following functional form:

relative difference of $t_i^{\dagger}s$ + temperature correction + wind correction yields direction

$$(t_i - t_{i+1}) + (t_i - t_{i+1}) \left(\sqrt{\frac{T_e}{T_{std}}} - 1 \right) + \frac{W}{V^2} S \cos \theta = \frac{S}{C} \sin A$$

⁶E. M. D'Arcy, 1977, "PASS 500 mb Rawinsonde Data," Vol 1 and 2, ECOM-DR-74-4, Atmospheric Sciences Laboratory, White Sands Missile Range, NM

EDITING AID AUTOMATED

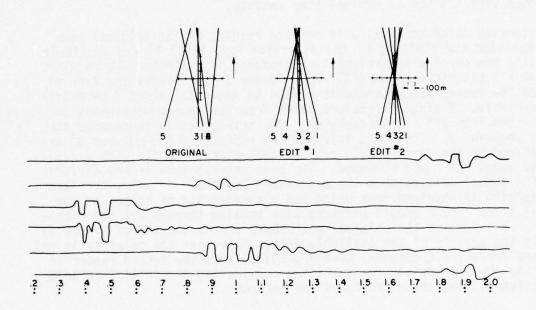


Figure 5. Automated aids available for selecting the arrival times from a single pressure wave passing through all six microphones.

$$\begin{aligned} & \left(t_1 - t_{1+1}\right) \sqrt{\frac{T_e}{T_{std}}} + \frac{W}{V^2} S \cos \theta = \frac{S}{C} \sin A \\ & t_1 - t_{1+1} = \left(\frac{S}{C} \sin A - \frac{W}{V^2} S \cos \theta\right) \sqrt{\frac{T_{std}}{T_e}} \\ & t_1 = t_{1+1} + \left(\frac{S}{C} \sin A - \frac{W}{V^2} S \cos \theta\right) \sqrt{\frac{T_{std}}{T_e}} \end{aligned}$$

where

t, = arrival time at microphone (sec)

T = effective temperature (°K)

 $T_{std} = 283.16$ °K

W = effective wind speed (m/sec)

θ = angle of the effective wind direction with respect to linear array of microphones (deg)

S = distance between adjacent microphones (m)

V = speed of sound at given temperature (m/sec)

C = speed of sound at std temperature (m/sec)

A = direction of sound with respect to perpendicular bisector of S

For the operation of this editing routine, the record reader picks the best defined signal from the six microphone traces on the GR-8 record. This signal, together with the microphone positions, meteorological message, and direction of the sound source, is required input to the EDIT 2 process which will provide a display of the six computed arrival times. The reader proceeds to locate the suggested point on each microphone trace then adjusts to select the arrival times that correspond to the selection criteria (break, valley, crossover, or peak) of the trace that initiated the EDIT 2 process. The research data base for the selected arrival times is contained in the appendix. The plots of the direction rays for each fix are also included to express their corresponding polygon of error.

EXPERIMENTAL RESULTS

The original microphone traces are categorized into usable and unusable sets of data. The unusable set contained those events wherein more than two microphone traces were unreadable. More events could have been usable had proper microphone attenuation adjustment been maintained. The unusable cases are not included in this data base and the planned sample size was reduced to the ranges listed in table 2; e.g., at the bottom of column 1 the entry 74/35 indicates the total events to be 74 and the usable data to be 35. In all, more than 1/2 of the experimental data was usable.

One of the high quality traces was used to postulate the accuracy of record reading. As a sample, seven record readers (professional scientists) were provided with a particular strip chart containing information obtained from six microphone traces. The readers were instructed to read the arrival time at the "break points" of the sound signature. The results indicated a sigma range of 3 to 9 milliseconds. The most accurate reading corresponded to a microphone trace with a well-defined signature, while the largest sigma (9 milliseconds) involved a microphone trace that contained interference. As discussed in the Record Reading section, this interference can be attenuated and well-defined balanced data can be provided to the record reader.

The original results derived from using the centroid method of sound ranging are listed in table 3. Comparing the miss-location distribution with table 4 indicates the improvement afforded by the use of automated assistance in record reading. The results of interest are the computed miss-distance from the actual source location. Figure 6 contains a set of 54 fixes on a surveyed target at 11.5 km and 13 degrees flank angle. The elliptical one probable error is used to illustrate the met interaction since the arrival times from the research data base are considered the actual arrivals. The axis center indicates the location of surveyed target 2, and the radial distance from the center to any point is the sound ranging miss-distance in fixing on the target. This scatter yields a distribution about a mean distance of 5 m in the cross and 54 m in the range. Overall the results are encouraging because this probable error is within the accepted 1.5 percent of target range accuracy.

CONCLUSIONS

The research arrival time data base is available, and the effect of proposed sound ranging meteorological messages can be evaluated. The position and size of the ellipse in figure 6 can be used as an indicator for selecting the actual effective met the sound experienced as it traveled from its origin to each microphone. The time and space variability between the measured met parameters and the path of propagation should also be considered in selecting the best meteorological correction technique.

TABLE 2. C4 EXPLOSIVE CHARGES CATEGORIZED AS TO TOTAL EVENTS/USABLE DATA.

Locations

Date	(1974)	1	2	3	4	5	6	7
1	Nov	3/1	5/5	4/2	5/2	3/0	0/0	0/0
2	Nov	7/3	9/9	7/7	6/5	7/0	0/0	0/0
4	Nov	7/1	9/2	7/1	6/1	7/0	0/0	0/0
6	Nov	3/2	5/5	4/3	4/4	4/4	0/0	0/0
7	Nov	8/3	8/2	7/4	6/6	7/6	0/0	0/0
8	Nov	2/1	5/5	4/3	4/4	4/3	0/0	0/0
11	Nov	3/1	5/1	4/0	4/0	3/0	0/0	0/0
12	Nov	3/3	5/3	4/2	4/3	4/3	0/0	0/0
	Nov	8/4	8/0	7/3	6/4	7/6	0/0	0/0
15	Nov	6/4	7/5	8/6	6/6	5/3	0/0	0/0
18	Nov	3/1	5/4	4/4	4/4	4/1	0/0	0/0
	Nov	2/0	3/2	2/2	2/2	1/0	2/0	9/3
	Nov	1/0	3/1	3/0	2/1	1/0	5/2	4/0
	Nov	3/0	4/1	4/1	4/1	2/1	9/6	9/0
	Nov	2/1	3/1	2/0	2/0	1/0	5/4	5/3
	Nov	2/1	3/3	2/2	2/2	1/0	5/0	5/0
	Dec	3/2	5/4	4/3	4/3	3/1	9/6	9/5
	Dec	2/1	3/3	2/2	2/2	1/0	7/1	5/1
-	Dec	3/3	3/2	3/2	4/4	2/0	13/0	1/0
	Dec	3/3	6/6	6/4	5/3	2/1	11/3	11/3
	-	74/35	104/64	88/51	82/57	69/29	66/22	58/15

TABLE 3. CUMULATIVE FREQUENCY OF LOCATION MISSES FROM ORIGINAL ANALYSIS USING THE CENTROID METHOD OF SOUND RANGING

Target No.	1	2	3	4	5	6	7
Range (km)	11.5	11.5	11.5	11.5	11.5	16.0	16.0
Flank (deg)	25	13	0	-13	-25	-9	-23
Radial Miss (m)							
25	0	1	2	1	0	0	0
50	0	3	2	3	0	2	0
75	1	6	8	5	0	4	0
100	1	6	12	10	1	5	0
150	2	10	19	15	6	11	0
200	5	17	21	16	6	12	0
300	9	23	32	24	9	13	4
400	11	30	37	26	14	14	6
500	11	35	38	28	18	16	7
600	12	39	40	31	20	17	9
700	13	41	41	33	21	19	9
800	14	42	43	33	23	19	9
900	18	44	44	36	24	20	10
>1000	39	59	51	44	38	34	25

TABLE 4. CUMULATIVE FREQUENCY OF LOCATION MISSES FROM AUTOMATED ASSIST ANALYSIS USING THE CENTROID METHOD OF SOUND RANGING.

Target No.	1	2	3	4	5	6	7
Range (km)	11.5	11.5	11.5	11.5	11.5	16.0	16.0
Flank (deg)	25	13	0	-13	-25	-9	-23
Radial Miss (m)							
25	1	2	3	4	0	0	0
50	4	14	8	9	3	1	1
75	8	19	17	19	4	6	1
100	11	27	25	23	12	8	4
150	18	40	35	33	16	10	5
200	23	48	38	40	19	11	6
300	24	54	43	44	22	15	8
400	25	54	43	44	24	15	10
>400	39	59	51	44	38	34	25

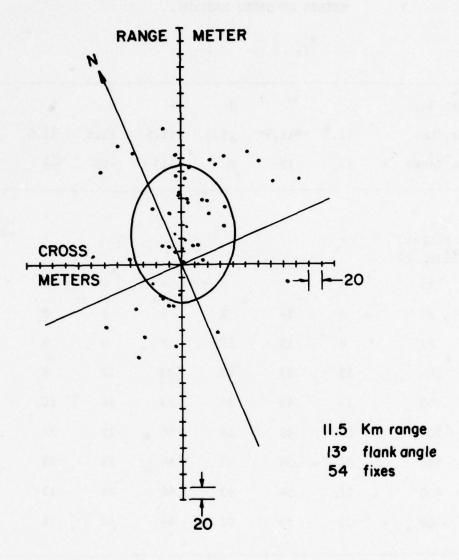


Figure 6. Illustrates the 54 fixes for source location 2 with the one probable error ellipse. The sound ranging method employed is the geometric with the centroid solution of direction ray intersection.

In comparing proposed solution algorithms, one must consider that the nature of some algorithms contains editing procedures, for example, the centroid versus the median solution. Using this data base the improvement of the median solution will be limited because the arrival times have already been adjusted to their most representative value. Therefore, the median solution will fix on the center of the ray intersection distribution which has already been edited.

A final comment that this analysis suggests is that expert supervision of adjusting microphone attenuation and reading microphone records should be maintained. If this procedure is followed, more long-range targets may be located by the sound ranging method.

REFERENCES

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APPENDIX

SOUND RANGING ARRIVAL TIME DATA FROM THE GR-8 DATA RECORDS COLLECTED DURING "PASS"

Table Al identifies the fix with the date and time of day.

The data base is listed in the following format: fix number, selected arrival time for microphones 1 through 6, and met data used to make corrections on fix.² The data base is listed normalized to the earliest arrival time indicating the effect of met during the same day. Finally a plot of the direction rays is included for each of the listed cases. The wind direction and relative wind speed are also illustrated to the right of each polygon of error. The order of plots is from left to right, and the scale is 100 m per grid.

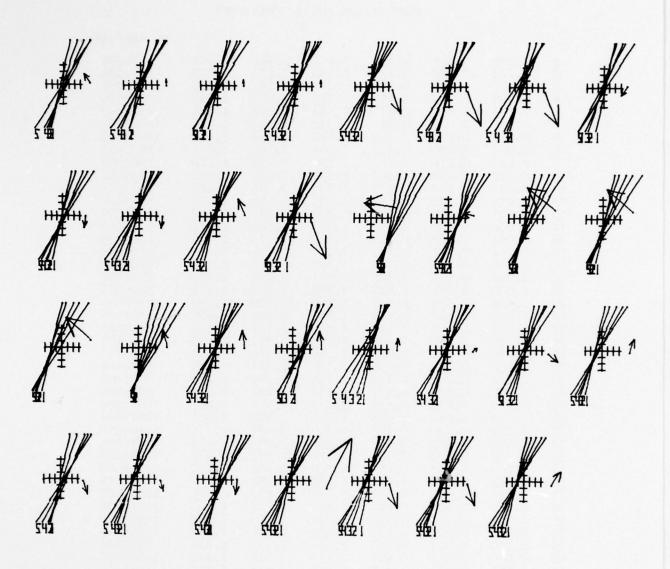
A. J. Blanco, 1978, "Long-Range Artillery Sound Ranging: "PASS" Meteorological Application," ASL-TR-0014, Atmospheric Sciences Laboratory, White Sands Missile Range, NM.

TABLE A1. TIME OF DAY FOR EACH FIX IN DATA BASE

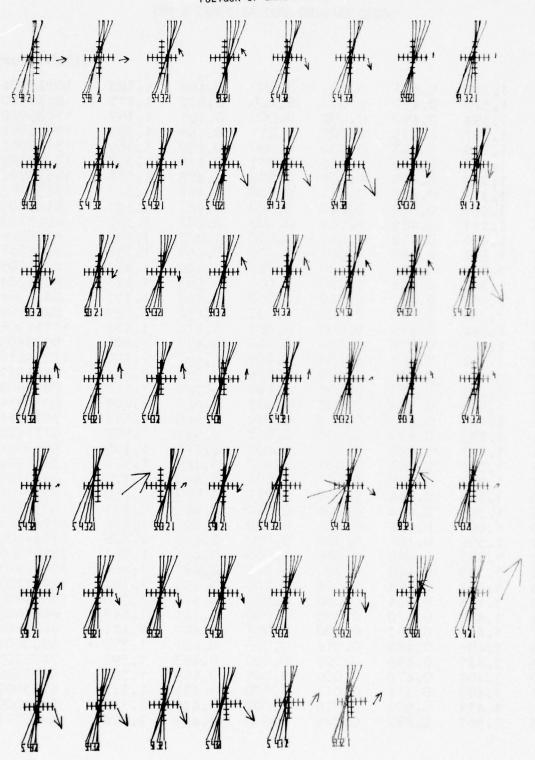
Date (1974)	1	2		Source Location			
Colonial Colonial			3	4	5	6	7
Nov	1 614	1 414 2 514	1 655	1 714 2 755			
		3 626	2 738	2 /55			-
		4 712					-
Nov		5 501	3 559	3 458			-
	2 450	6 540 7 656	4 727 5 807	4 724 5 900			:
	3 1035	8 741	6 908	6 955			-
	4 1152	9 818 10 855	7 1013 8 1155	7 1120			-
		11 1058					-
Nov	5 458	12 443	9 536	8 955			-
Nov	6 723	13 511 14 658	10 741		1 700		-
	7 746	15 819	11 833	9 649 10 721	1 700 2 757		
		16 845 17 931	12 927		3 835 4 951		-
Nov	8 622	18 632	13 444	11 354	5 411		-
	9 720 10 825	19 737	14 619 15 722	12 425 13 829	6 540 7 634		- :
			16 846		8 740		
				14 1045	9 844 10 1033		-
Nov		20 1257 21 1340	17 1247 18 1520	15 1336 16 1452	11 1425 12 1523		
	11 1216	22 1448	19 1642	17 1538	13 1731		-
	11 1316	23 1535					-
1 Nov	12 530	24 646					-
2 Nov	13 556 14 757		20 421 21 759			===	-
4 Nov	15 425		22 454	18 356	14 643		
	16 524		23 724	19 839	15 741		-
	17 721		24 1121	20 930 21 1045	16 851 17 1031		
					18 1136		-
5 Nov	18 634	25 704	25 430	22 457			-
	19 740 20 805	26 752 27 833	26 500	23 538	19 637 20 800		
		28 1034	27 736 28 745	24 836	20 800		-
	21 1057	29 1114	29 854 30 1151	25 953 26 1204			-
8 Nov	22 520	30 455			21 721		
o NOV		31 558	31 419 32 601	27 452 28 516	21 721		- :
		32 810 33 849	33 751 34 808	29 706 30 754			
			34 500				
9 Nov		34 540 35 817		31 613 32 716			1 6 2 8
				32 710			3 8
20 Nov		36 1339				1 1535	
				22 715	22 756		
23 Nov		37 635		33 715	22 756	2 805 3 1205	
						4 1305	-
		***				5 1405	
6 Nov		38 1235				6 1505	4 12
	23 1215						5 13 6 15
7 Nov	24 1255	39 935	35 955	34 1015			
.,	***	40 1215		35 1131			
		41 1315					-
2 Dec	25 515	40 535	36 555	36 717	23 657	7 705	7 5
	26 856	42 535 43 817	37 757	37 1022 38 1115		8 905 9 905	8 6 9 8
		43 817 44 916	38 1004			10 1007	10 10
						11 1105	11 12
3 Dec	27 545	45 605 46 845	39 625 40 825	39 645 40 745		12 642	12 5
5 Dec		47 945	***				
		48 1135		41 1315		***	
	28 1115			42 1615 43 1715			
7 Dec	29 536	49 550 50 815	41 603 42 755	44 615 45 715	24 658	13 705 14 805	13 5 14 6
	30 855	51 915	43 1355	46 1416		15 905	15 8
	31 1255	52 1215 53 1315	1				
	51 1255	54 1515		***			

SOURCE 1
SOUND RANGING ARRIVAL TIMES & MET

							.1°C/10m/knots
1234567890112314567890 1011234567890	0.000 0.000	0.946 0.914 0.906 0.890 0.890 0.912 0.924 0.924 0.924 0.924 0.924 0.924 0.924 0.924 0.938 0.943 0.873 0.888 0.975 1.044 0.925 0.936 0.911 0.936 0.937 0.936	2.292 2.217 2.231 2.201 2.242 2.172 2.281 2.285 2.285 2.285 2.286 2.192 2.400 2.370 2.502 2.198 2.259 2.148 2.259 2.2184 2.228 2.281	9952625458254.9912958466233333333333333333333333333333333333	6.9091 6.9091 6.9091 6.9092 6.9002 6.	8.349 8.198 8.194 8.170 8.283 8.118 8.251 8.376 8.395 8.165	10128804 15535702 15535702 15535702 15535702 5463609 9063313 8511204 8005304 11131306 7063314 6821314 6821314 6821314 6821304 6025914 5526313 5526313 8833506 8235106 10037804 11146502 10258305 13240105 6863805 5200604 7405305 11841820 6763809
31	0.000	0.929	2.269	3.970 3.975	5.999 5.999	8.305 8.300	5663808 9843706

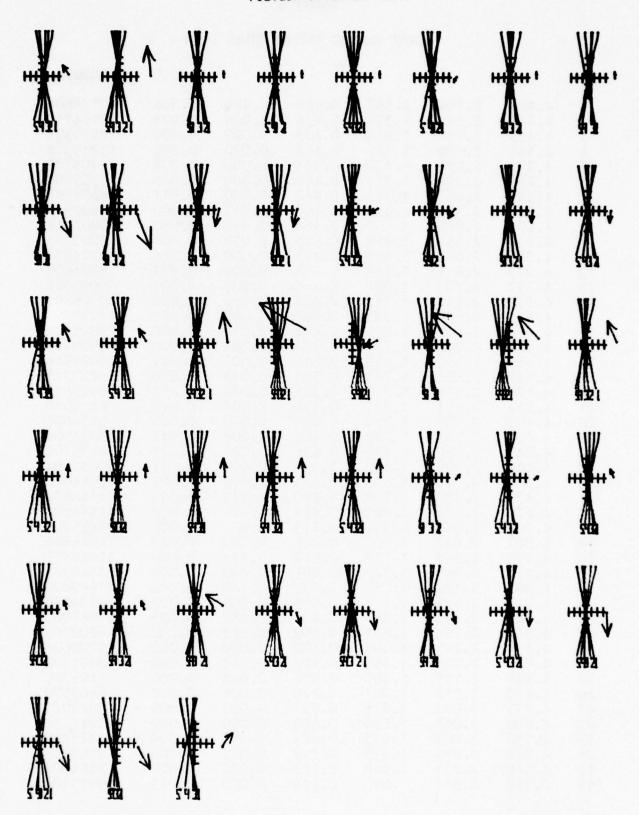


SOURCE 2
SOUND RANGING ARRIVAL TIMES & MET

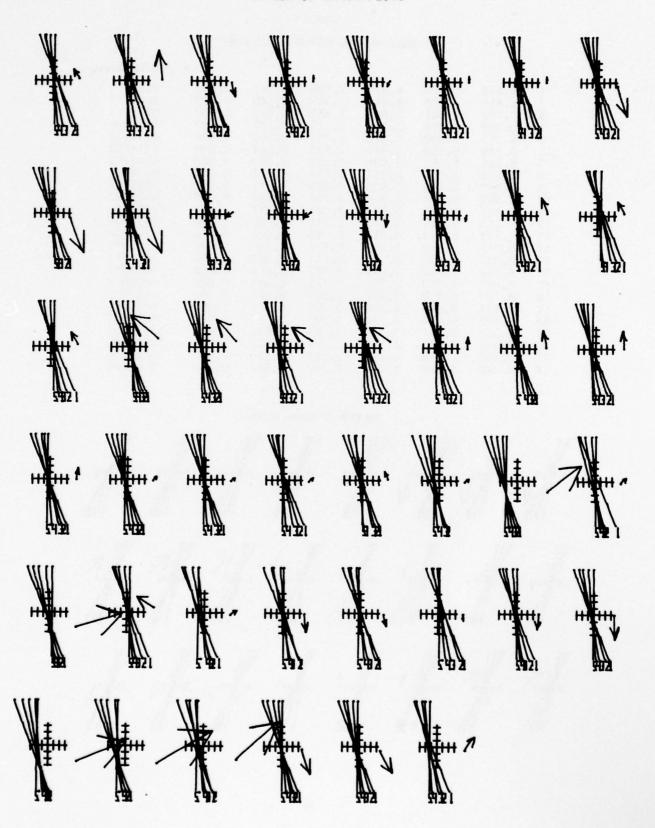


SOURCE 3
SOUND RANGING ARRIVAL TIMES & MET

							.1°C/10mi/knots
123456789012345678901234567890123	1.388 1.373 1.377 1.377 1.377 1.379 1.379 1.401 1.401 1.335 1.388 1.388 1.388 1.388 1.388 1.388 1.388 1.388 1.388 1.371	0.471 0.457 0.480 0.473 0.460 0.474 0.484 0.484 0.489 0.469 0.469 0.479 0.479 0.479 0.489 0.499	0.009 0.000 0.003 0.000 0.000 0.000 0.001 0.005 0.000	0.000 0.025 0.000 0.011 0.000 0.011 0.002 0.000 0.000 0.000 0.000 0.002 0.002 0.002 0.002 0.002 0.002 0.002 0.002 0.009 0.009 0.009 0.009 0.000 0.000 0.000 0.000 0.000 0.000 0.000	0.468 0.468 0.460 0.475 0.467 0.475 0.467 0.475 0.476 0.476 0.477 0.477 0.477 0.477 0.477 0.477 0.477 0.477 0.477 0.477 0.477 0.477 0.477 0.477 0.479	1.388 1.473 1.389 1.3796 1.3791 1.3791 1.3791 1.4123 1.4123 1.4123 1.4123 1.4123 1.4123 1.4123 1.4123 1.4123 1.423	10128804 8134710 13035902 13035902 13035902 13209302 15535702 15535702 5463609 9063313 8606606 8214603 8511204 8005304 8005304 11131306 9929405 12234310 8524521 7015905 6025914 5027311 8731208 9236604 9236604 8235106 8235106 11944602 11146502 12931203
32 33 34 35	1.383 1.329 1.393 1.313						
36 37 38 39	1.459 1.429 1.404 1.427	0.520 0.484 0.487 0.499	0.020 0.000 0.016 0.009	0.000 0.007 0.000 6.000	0.449 0.487 0.467 0.463	1.349 1.411 1.376 1.393	6863805 6202706 5200604 7405305
40 41 42 43	1.401 1.463 1.431 1.387	0.478 0.514 0.506 0.482	0.000 0.017 0.019 0.015	0.005 0.000 0.000 0.000	0.469 0.435 0.449 0.469	1.382 1.342 1.333 1.404	6403508 6763809 5461809 9843706



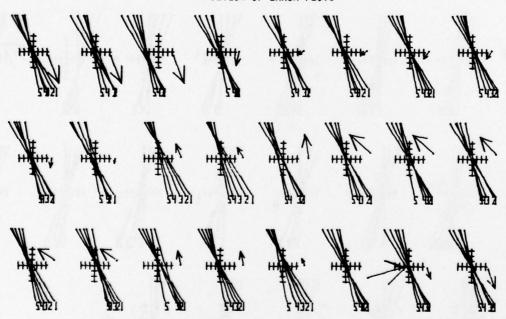
SOURCE 4
SOUND RANGING ARRIVAL TIMES & MET



SOURCE 5
SOUND RANGING ARRIVAL TIMES & MET

							.1°C/10m/knots
1	8.449	6.103	4.039	2.309	0.941	0.000	9063313
2	8.455	6.125	4.060	2.305	0.940	0.000	9063313
3	8.122	5.844	3.844	2,167	0.872	0.000	9063313
4	8.202	5.920	3.917	2.226	0.897	0.000	8606606
5	8.293	5.990	3.950	2.234	0.909	0.000	8214603
6	8.149	5.856	3.852	2.183	0.881	0.000	8214603
7	8.244	5.945	3.926	2.227	0.900	0.000	8511204
8	8.270	5.967	3.937	2.231	0.902	0.000	8511204
9	8.250	5.949	3.920	2.225	0.911	0.000	8005304
10	8.201	5.911	3.911	2.226	0.896	0.000	9905802
11	8.327	6.006	3.961	2.245	0.913	0.000	11131306
12	8.268	5.947	3.912	2.215	0.899	0.000	9929405
13	8.111	5.835	3.830	2.148	0.868	0.000	12234310
14	8.013	5.750	3.764	2.121	0.849	0.000	5526313
15	8.023	5.768	3.788	2.131	0.841	0.000	5526313
16	8.094	5.820	3.818	2.159	0.876	0.000	5027311
17 18	7.997	5.730 5.878	3.755 3.878	2.113	0.846	0.000	64 25010
19	8.157 8.354	6.039	4.000	2.200	0.900	0.000	64 25010 8833506
20	8.220	5.920	3.900	2.206	0.890	0.000	8833506
21	8.245	5.937	3.910	2.209	0.890	0.000	12931203
22	8.855	6.445	4.307	2.492	1.036	0.000	11949820
23	8.390	6.070	4.021	2.291	0.939	0.000	6863805
24	8.448	6.108	4.046	2.300	0.942	0.000	6763809
- 7	0.440	0.100	7.040	700	0.742	0.000	0,0000

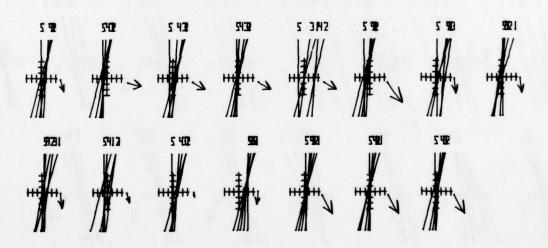
POLYGON OF ERROR PLOTS



SOURCE 6
- SOUND RANGING ARRIVAL TIMES & MET

						1. 1.	.1°C/10mi/knots
1	3.334	2.057	1.063	0.375	0.008	0.000	15200205
2	3.365	2.079	1.075	0.380	0.020	0.000	11453907
3	3.471	2.155	1.125	0.404	0.021	0.000	12656407
4	3.420	2.116	1.099	0.396	0.030	0.000	12656407
5	3.524	2.211	1.143	0.439	0.008	0.000	12656407
6	3.360	2.076	1.074	0.384	0.014	0.000	15060411
7	3.423	2.121	1.114	0.392	0.010	0.000	6202706
8	3.305	2.009	1.023	0.360	0.012	0.000	6202706
9	3.380	2.068	1.073	0.370	0.018	0.000	6202706
10	3.299	2.031	1.031	0.335	0.000	0.009	5200604
11	3.356	2.060	1.049	0.359	0.000	0.003	8001102
12	3.431	2.128	1.115	0.417	0.045	0.000	7405305
13	3.501	2.172	1.141	0.427	0.039	0.000	5461809
14	3.431	2.116	1.105	0.402	0.029	0.000	5461809
15	3.454	2.145	1.118	0.407	0.026	0.000	5461809

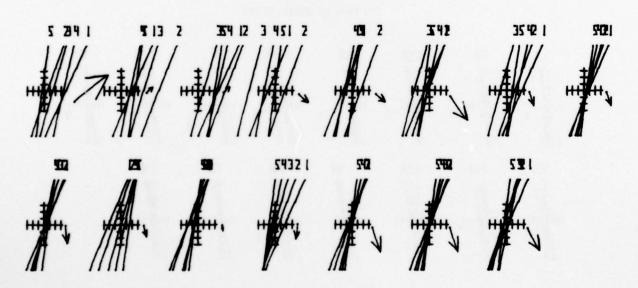
POLYGON OF ERROR PLOTS



SOURCE 7
SOUND RANGING ARRIVAL TIMES & MET

							.1°C/10mi/knots
1	6.863	4.914	3.271	1.880	0.741	0.000	12846517
2	6.667	4.821	3.134	1.764	0.736	0.000	12345503
3	6.646	4.772	3.119	1.812	0.746	0.000	12345503
4	6.273	4.466	2.854	1.650	0.688	0.000	10258305
5	6.357	4.557	2.950	1.671	0.696	0.000	10258305
6	6.351	4.531	2.950	1.693	0.682	0.000	15060411
7	6.501	4.626	3.023	1.748	0.707	0.000	6863805
8	6.449	4.606	3.021	1.707	0.694	0.000	6863805
9	6.395	4.568	2.988	1.690	0.694	0.000	6202706
10	6.372	4.582	3.030	1.732	0.717	0.000	5200604
11	6.220	4.435	2.906	1.630	0.658	0.000	8001102
12	6.300	4.460	2.890	1.610	0.640	0.000	7405305
13	6.405	4.580	3.003	1.694	0.687	0.000	6763809
14	6.450	4.612	3.021	1.709	0.694	0.000	6763809
15	6.483	4.625	3.036	1.723	0.693	0.000	5461809

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